

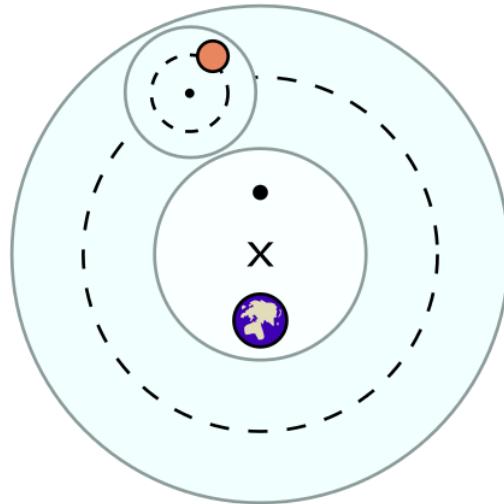
# Magnetic fields Generated by Magnets Moving Along Epicyclic Paths

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# Introduction (Epicyclic Paths)

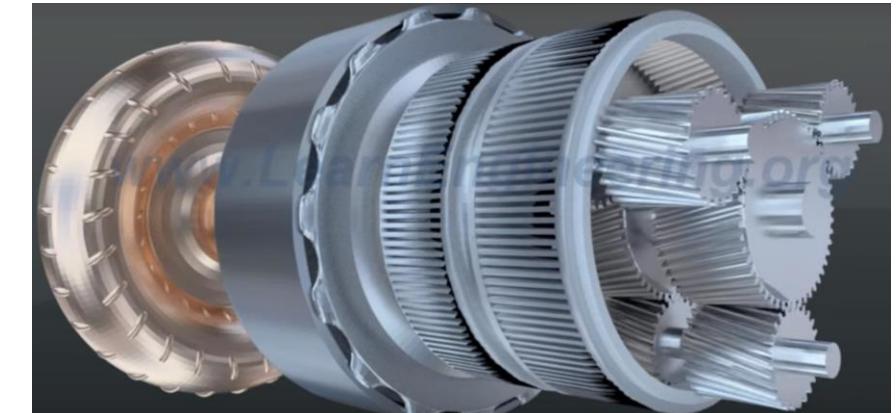
- Epicycle: “circle moving on another circle” -- Greek Astronomer
- Describe apparent relative positions of Sun, Moon, Earth, planets.



[https://en.wikipedia.org/wiki/Deferent\\_and\\_epicycle](https://en.wikipedia.org/wiki/Deferent_and_epicycle)



<http://www.unicyclist.com/forums/showthread.php?t=120161>



[https://www.youtube.com/watch?v=u\\_y1s8C0Hmc](https://www.youtube.com/watch?v=u_y1s8C0Hmc)

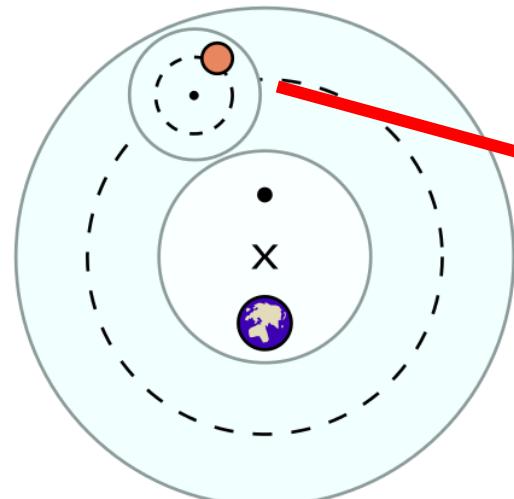
- used in wrist watches, automobiles, bicycles, PVD, ...



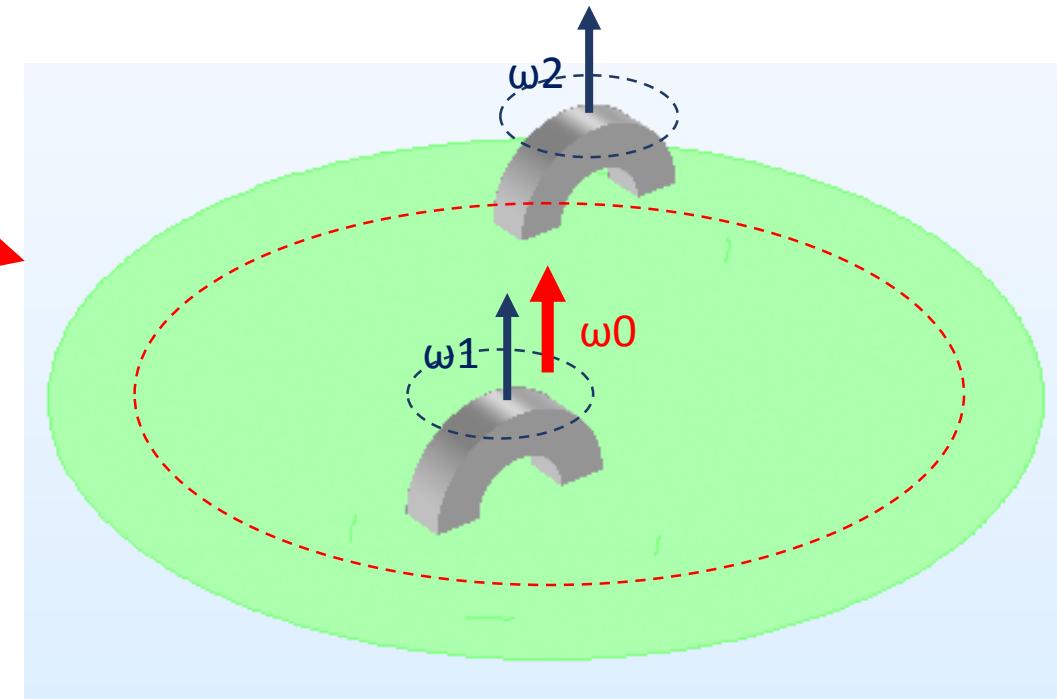
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# Motivation

- Study magnetic field distributions generated by magnets moving in epicyclic paths
- Implement epicyclic motion of magnets in magnetostatic simulation



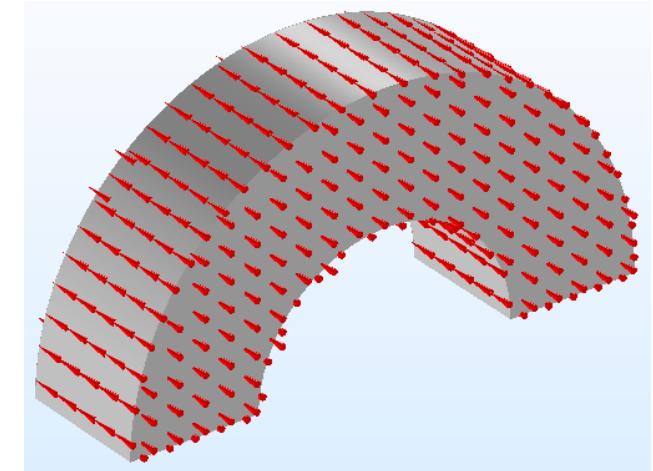
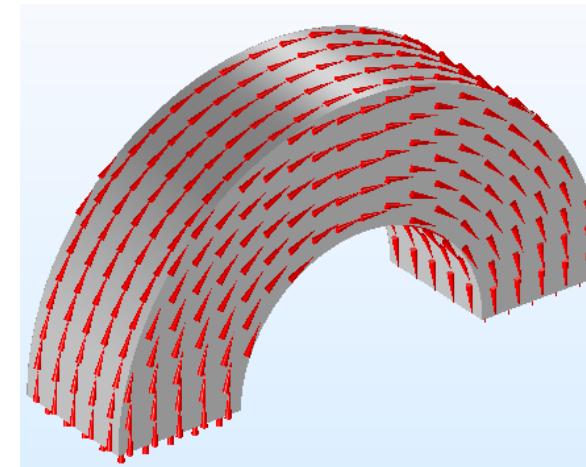
[https://en.wikipedia.org/wiki/Deferent\\_and\\_epicycle](https://en.wikipedia.org/wiki/Deferent_and_epicycle)



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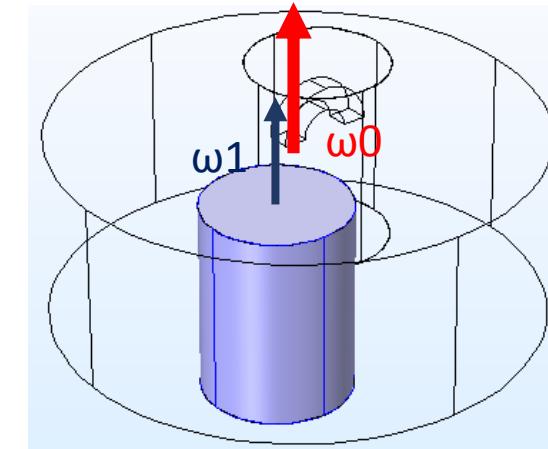
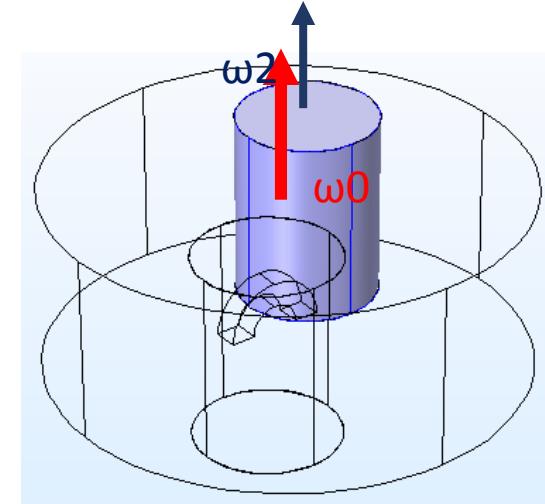
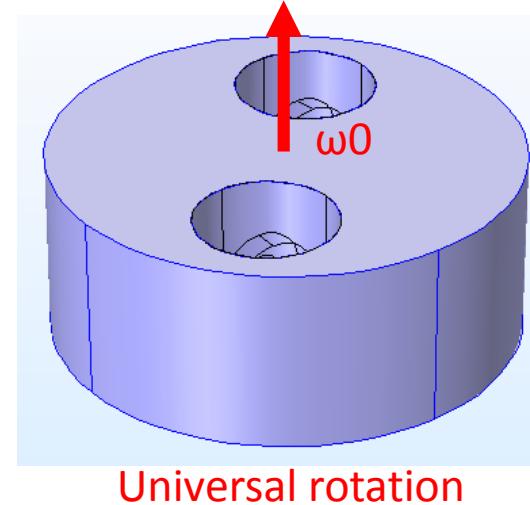
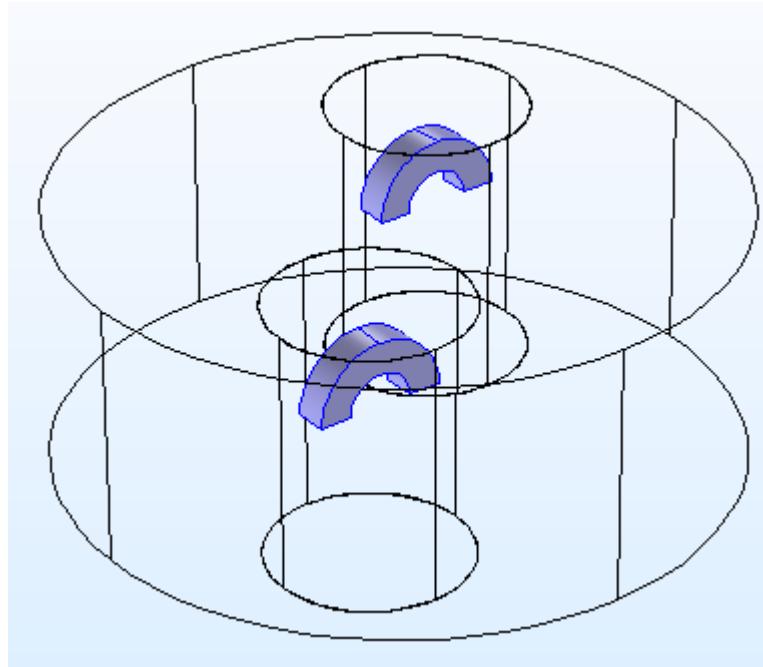
# Model

- Horseshoe magnets
- Finding out magnetization( $M$ ) configurations within magnets
- Curvilinear coordinates



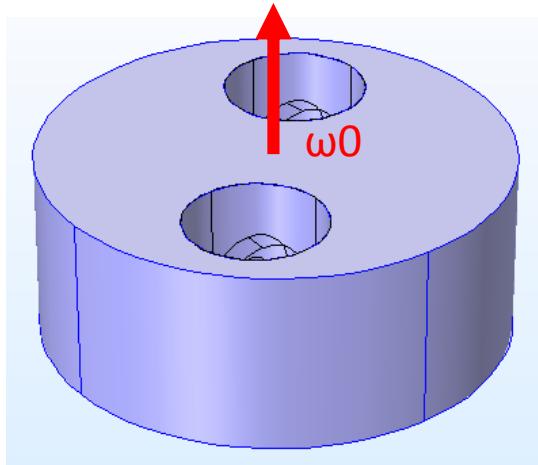
# Model

- Magnetic Fields no current
- Deformed Mesh



# Model

- Universal Rotation

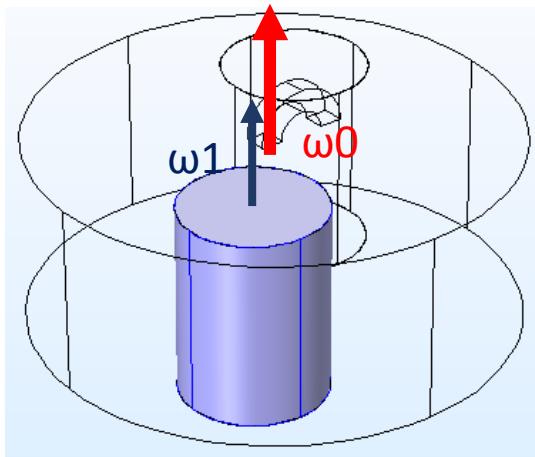


$$\begin{bmatrix} x_{universal}(x_0, y_0, t) \\ y_{universal}(x_0, y_0, t) \\ z_{universal}(t) \end{bmatrix} = \begin{bmatrix} \cos(\omega_0 t) & -\sin(\omega_0 t) & 0 \\ \sin(\omega_0 t) & \cos(\omega_0 t) & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_0 - x_{0,Center} \\ y_0 - y_{0,Center} \\ z_0 \end{bmatrix}$$



# Model

- Self-rotation



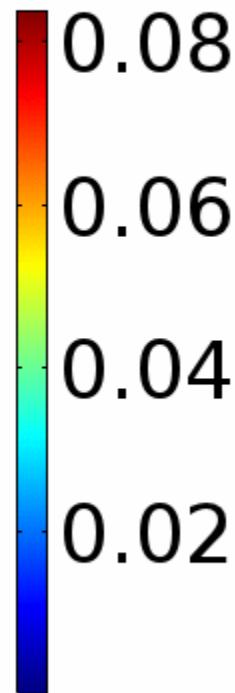
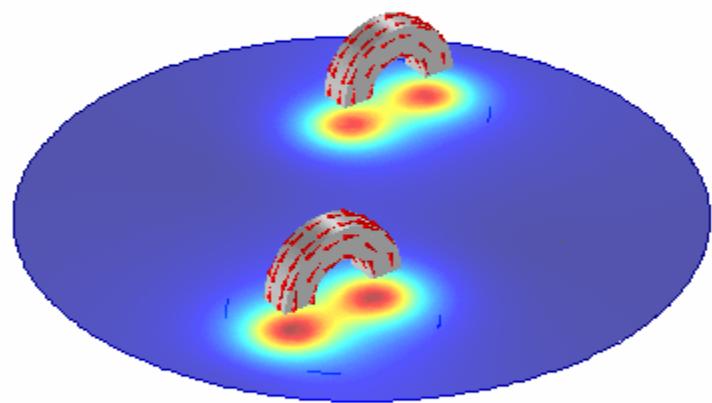
$$\begin{bmatrix} x_{1,center}(t) \\ y_{1,center}(t) \end{bmatrix} = \begin{bmatrix} x_{universal}(x_{1,center}(0), y_{1,center}(0), t) \\ y_{universal}(x_{1,center}(0), y_{1,center}(0), t) \end{bmatrix}$$

$$\begin{bmatrix} x_1(t) \\ y_1(t) \\ z_1(t) \end{bmatrix} = \begin{bmatrix} \cos(\omega_1 t) & -\sin(\omega_1 t) & 0 \\ \sin(\omega_1 t) & \cos(\omega_1 t) & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_{universal}(t) - x_{1,center}(t) \\ y_{universal}(t) - y_{1,center}(t) \\ z_0 \end{bmatrix}$$

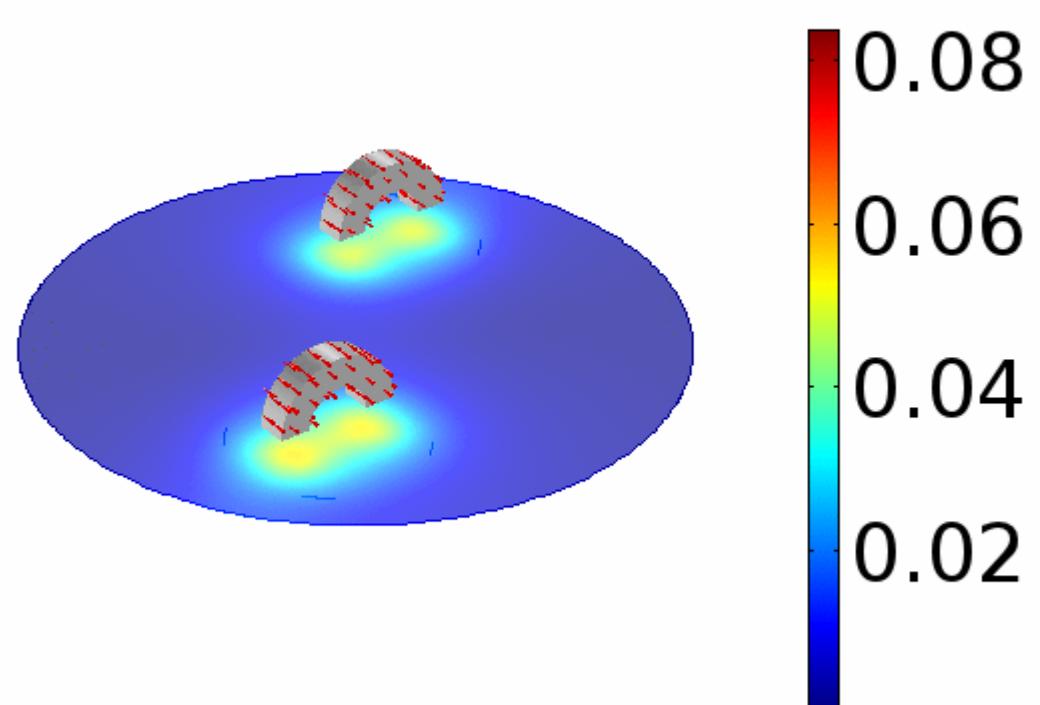
- Similarly for  $\omega_2$  rotation



# Results



<http://www.pitotech.com.tw/Magnetic%20Configuration%201.gif>



<http://www.pitotech.com.tw/Magnetic%20Configuration%202.gif>



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Thank you



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